

# MATH 2670: Quiz #3 – SOLUTIONS

/5 **Problem 1:** Evaluate the surface integral  $\int_S xz^2 dS$  where  $S$  is the part of the cone  $y = \sqrt{x^2 + z^2}$  above the  $xy$ -plane and between the planes  $y = 0$  and  $y = 5$ .

Hint: you can parameterize  $S$  with the vector function  $\mathbf{r}(R, \theta) = (R \cos \theta, R, R \sin \theta)$ .

$$\mathbf{r}(R, \theta) = (R \cos \theta, R, R \sin \theta) \implies \begin{aligned} \mathbf{r}_R &= (\cos \theta, 1, \sin \theta) \\ \mathbf{r}_\theta &= (-R \sin \theta, 0, R \cos \theta) \end{aligned} \quad (\theta, R) \in D = [0, \pi] \times [0, 5]$$

$$\mathbf{r}_R \times \mathbf{r}_\theta = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \cos \theta & 1 & \sin \theta \\ -R \sin \theta & 0 & R \cos \theta \end{vmatrix} = R \cos \theta \hat{\mathbf{i}} - R \hat{\mathbf{j}} + R \sin \theta \hat{\mathbf{k}}$$

$$\implies |\mathbf{r}_R \times \mathbf{r}_\theta| = \sqrt{(R \cos \theta)^2 + R^2 + (R \sin \theta)^2} = \sqrt{2}R$$

$$\begin{aligned} \implies \int_S xz^2 dS &= \iint_D xz^2 |\mathbf{r}_R \times \mathbf{r}_\theta| dA \\ &= \int_0^\pi \int_0^5 (R \cos \theta)(R \sin \theta)^2 \sqrt{2}R dR d\theta \\ &= \sqrt{2} \underbrace{\int_0^\pi \sin^2 \theta \cos \theta d\theta}_{\frac{1}{3} \sin^3 \theta \Big|_0^\pi = 0} \int_0^5 R^4 dR = \boxed{0} \end{aligned}$$

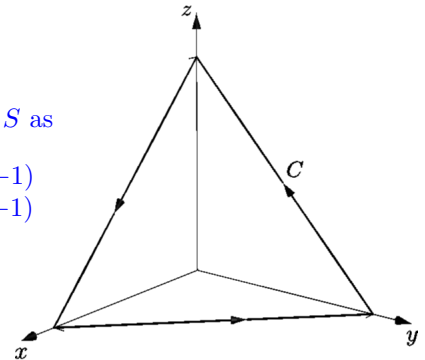
/5 **Problem 2:** Use Stokes' Theorem to evaluate  $\oint_C \mathbf{F} \cdot d\mathbf{r}$  where  $\mathbf{F}(x, y, z) = (x + y)\hat{\mathbf{i}} + (y + z)\hat{\mathbf{j}} + (z + x)\hat{\mathbf{k}}$  and  $C$  is triangle with vertices  $(1, 0, 0)$ ,  $(0, 1, 0)$  and  $(0, 0, 1)$ .

Let  $S$  be the triangular planar region bounded by  $C$ . We can parameterize  $S$  as

$$\mathbf{r}(x, y) = (x, y, 1 - x - y) \implies \begin{aligned} \mathbf{r}_x &= (1, 0, -1) \\ \mathbf{r}_y &= (0, 1, -1) \end{aligned}$$

where  $(x, y) \in D =$  the triangular region in the  $xy$ -plane that lies below  $S$ . The surface normal consistent with the orientation of  $C$  is in the direction

$$\mathbf{r}_x \times \mathbf{r}_y = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ 1 & 0 & -1 \\ 0 & 1 & -1 \end{vmatrix} = \hat{\mathbf{i}} + \hat{\mathbf{j}} + \hat{\mathbf{k}}.$$



We have

$$\nabla \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x+y & y+z & z+x \end{vmatrix} = -\hat{\mathbf{i}} - \hat{\mathbf{j}} - \hat{\mathbf{k}}.$$

Stokes' Theorem gives

$$\begin{aligned} \oint_C \mathbf{F} \cdot d\mathbf{r} &= \iint_S \nabla \times \mathbf{F} \cdot d\mathbf{S} = \iint_D \nabla \times \mathbf{F} \cdot (\mathbf{r}_x \times \mathbf{r}_y) dA \\ &= \iint_D (-1, -1, -1) \cdot (1, 1, 1) dA = -3 \underbrace{\iint_D dA}_{1/2} = \boxed{-\frac{3}{2}} \end{aligned}$$